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# **grg-mpdata Documentation**

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Contents:



### 1.1 Overview

grg-mpdata is a minimalist python package to support the reading and writing of [Matpower](#) network data files.

The primary entry point of the library is `grg_mpdata.io` module, which contains the methods for data input and output.

### 1.2 Installation

Simply run:

```
pip install grg-mpdata
```

### 1.3 Testing

grg-mpdata is designed to be a library that supports other software. It is not immediately useful from the terminal. However, you can test the parsing functionality from the command line with:

```
python -m grg_mpdata.io <path to Matpower case file>
```

If this command is successful, you will see a simplified plain text version of the network data printed to the terminal.

### 1.4 Compatibility

The following features of the [Matpower 5.1](#) specification are not replicated in this library,

1. The following fields are not supported, 'A', 'I', 'u', 'H', 'Cw', 'N', 'fparm', 'z0', 'zl', 'zu'

- 
2. The matrix columns are not extensible



### 2.1 grg\_mpdata.io module

functions for reading and writing matpower data files

`grg_mpdata.io.build_cli_parser()`

`grg_mpdata.io.main(args)`

reads a matpower case file from a command line arguments and prints the parsed file to stdout

**Parameters** `args` – an argparse data structure

`grg_mpdata.io.parse_mp_case_file(mpFileName)`

opens the given path and parses it as matpower data

**Parameters** `mpFileName (str)` – path to the a matpower data file

**Returns** a grg\_mpdata case

**Return type** *Case*

`grg_mpdata.io.parse_mp_case_lines(mpLines)`

parses a list of strings as matpower data

**Parameters** `mpLines (list)` – the list of matpower data strings

**Returns** a grg\_mpdata case

**Return type** *Case*

`grg_mpdata.io.parse_mp_case_str(mpString)`

parses a given string as matpower data

**Parameters** `mpString (str)` – a matpower data file as a string

**Returns** a grg\_mpdata case

**Return type** *Case*

`grg_mpdata.io.write_mp_case_file(output_file_location, case)`  
writes a matpower case file

**Parameters**

- **output\_file\_location** (*str*) – the path of the file to write
- **case** (*Case*) – the data structure to write out

## 2.2 grg\_mpdata.cmd module

functions for analyzing and transforming matpower data files

`grg_mpdata.cmd.build_cmd_parser()`

`grg_mpdata.cmd.compare_component_lists(list_1, list_2, comp_name, index_name='index')`  
compares two lists and prints the differences to stdout. Objects in the lists are assumed to have an identification attribute.

**Parameters**

- **list\_1** (*list*) – the first list
- **list\_2** (*list*) – the second list
- **comp\_name** (*string*) – the name of components being compared
- **index\_name** (*string*) – the name of the object identification attribute

**Returns (int):** returns the number of items that differed in the two lists

`grg_mpdata.cmd.diff(case_1, case_2)`  
Compares two `grg_mpdata.struct.Case` objects and prints the differences to stdout.

**Parameters**

- **case\_1** – the first Matpower case
- **case\_2** – the second Matpower case

**Returns (int):** returns the number of items that differed in the two cases

`grg_mpdata.cmd.eq(case_1, case_2)`

`grg_mpdata.cmd.main(args)`  
reads a matpower case files and processes them based on command line arguments.

**Parameters** **args** – an argparse data structure

## 2.3 grg\_mpdata.exception module

a collection of all grg\_mpdata exception classes

**exception** `grg_mpdata.exception.MPDataException`

Bases: `exceptions.Exception`

root class for all MPData Exceptions

**exception** `grg_mpdata.exception.MPDataParsingError`

Bases: `grg_mpdata.exception.MPDataException`

for errors that occur while attempting to parse a matpower data file

**exception** `grg_mpdata.exception.MPDataValidationError`

Bases: `grg_mpdata.exception.MPDataException`

for errors that occur while attempting to validate the correctness of a parsed matpower data file

**exception** `grg_mpdata.exception.MPDataWarning`

Bases: `exceptions.Warning`

root class for all MPData Warnings

## 2.4 grg\_mpdata.struct module

data structures for encoding matpower data files

**class** `grg_mpdata.struct.Branch`(*index*, *f\_bus*, *t\_bus*, *br\_r*, *br\_x*, *br\_b*=0.0, *rate\_a*=0.0, *rate\_b*=0.0, *rate\_c*=0.0, *tap*=0.0, *shift*=0.0, *br\_status*=1, *angmin*=-360.0, *angmax*=360.0, *pf*=None, *qf*=None, *pt*=None, *qt*=None, *mu\_sf*=None, *mu\_st*=None, *mu\_angmin*=None, *mu\_angmax*=None)

Bases: `object`

This data structure contains key power network branch parameters. If the value of tap or shift are non-zero, the branch is considered a transformer. Angle difference bound arguments have default values for backward compatibility with an older data specification.

### Parameters

- **index** (*int*) – unique branch identifier
- **f\_bus** (*int*) – the identifier of the from bus
- **t\_bus** (*int*) – the identifier of the to bus
- **br\_r** (*float*) – the branch resistance (p.u.)
- **br\_x** (*float*) – the branch reactance (p.u.)
- **br\_b** (*float*) – the total branch charging susceptance (p.u.)
- **rate\_a** (*float*) – long term rating (MVA)
- **rate\_b** (*float*) – short term rating (MVA)
- **rate\_c** (*float*) – emergency rating (MVA)
- **tap** (*float*) – transformer off nominal turn ratio (p.u.)
- **shift** (*float*) – positive delay transformer phase shift (degrees)
- **br\_status** (*int*) – branch status (in service = 1, out of service = 0)
- **angmin** (*float*) – phase angle difference lower bound (degrees)
- **angmax** (*float*) – phase angle difference upper bound (degrees)
- **pf** (*float*, *optional*) – from bus active power flow (MW)
- **qf** (*float*, *optional*) – from bus reactive power flow (MVar)
- **pt** (*float*, *optional*) – to bus active power flow (MW)

- **qt** (*float, optional*) – to bus reactive power flow (MVar)
- **mu\_sf** (*float, optional*) – KKT multiplier on from bus long term rating limit (u/MVA)
- **mu\_st** (*float, optional*) – KKT multiplier on to bus long term rating limit (u/MVA)
- **mu\_angmin** (*float, optional*) – KKT multiplier on phase angle difference lower bound (u/degree)
- **mu\_angmax** (*float, optional*) – KKT multiplier on phase angle difference upper bound (u/degree)

**to\_matpower()**

Returns: a Matpower encoding of this data structure as a string

**validate()**

Checks that this data structure conforms to the Matpower data specification

```
class grg_mpdata.struct.Bus(bus_i, bus_type, pd, qd, gs, bs, area, vm, va, base_kv,  
                           zone, vmax, vmin, lam_p=None, lam_q=None, mu_vmax=None,  
                           mu_vmin=None)
```

Bases: object

This data structure contains key power network bus parameters.

#### Parameters

- **bus\_i** (*int*) – unique bus identifier
- **bus\_type** (*int*) – PQ = 1, PV = 2, reference = 3, disconnected = 4
- **pd** (*float*) – active power demand (MW)
- **qd** (*float*) – reactive power demand (MVar)
- **gs** (*float*) – shunt conductance (MW at 1.0 volts p.u.)
- **bs** (*float*) – shunt susceptance (MVar at 1.0 volts p.u.)
- **area** (*int*) – area identifier
- **vm** (*float*) – voltage magnitude (volts p.u.)
- **va** (*float*) – voltage angle (degrees)
- **base\_kv** (*float*) – base voltage (kilovolts)
- **zone** (*int*) – loss zone
- **vmax** (*float*) – voltage magnitude upper bound (volts p.u.)
- **vmin** (*float*) – voltage magnitude lower bound (volts p.u.)
- **lam\_p** (*float, optional*) – Lagrange multiplier on active power KCL (u/MW)
- **lam\_q** (*float, optional*) – Lagrange multiplier on reactive power KCL (u/MVar)
- **mu\_vmax** (*float, optional*) – KKT multiplier on voltage upper bound (u/volts p.u.)
- **mu\_vmin** (*float, optional*) – KKT multiplier on voltage lower bound (u/volts p.u.)

**to\_matpower()**

Returns: a Matpower encoding of this data structure as a string

**validate()**

Checks that this data structure conforms to the Matpower data specification

```
class grg_mpdata.struct.BusName (index, name)
```

Bases: object

This data structure contains bus name parameters.

#### Parameters

- **index** (*int*) – unique identifier for this bus name
- **name** (*str*) – a bus name

```
to_matpower ()
```

Returns: a Matpower encoding of this data structure as a string

```
validate ()
```

Checks that this data structure conforms to the Matpower data specification

```
class grg_mpdata.struct.Case (name=None, version=None, baseMVA=None, bus=None,  

                             gen=None, branch=None, gencost=None, dcline=None,  

                             dclinecost=None, busname=None)
```

Bases: object

This data structure contains lists of all the key components in a power network. All arguments have default values to allow clear error messages to be generated in the validation method. At this time, only Matpower case version 2 is supported.

#### Parameters

- **name** (*str*) – textual name of the test case. Must be a valid matlab function identifier
- **version** (*str*) – indicates the version of the test case
- **baseMVA** (*float*) – the network MVA base value (MVA)
- **bus** (*list of Bus*) – network buses
- **gen** (*list of Generator*) – network generators
- **branch** (*list of Branch*) – network branches
- **gencost** (*list of GeneratorCost, optional*) – generator cost models
- **dcline** (*list of DCLine, optional*) – network DC lines
- **dclinecost** (*list of DCLineCost, optional*) – DC line cost models
- **busname** (*list of BusName, optional*) – string names of items in bus list

```
remove_status_zero ()
```

```
to_matpower ()
```

Returns: a Matpower encoding of this data structure as a string

```
validate ()
```

Checks that this data structure conforms to the Matpower data specification.

```
class grg_mpdata.struct.DCLine (index, f_bus, t_bus, br_status, pf, pt, qf, qt, vf, vt, pmin, pmax,  

                             qminf, qmaxf, qmint, qmaxt, loss0, loss1, mu_pmin=None,  

                             mu_pmax=None, mu_qminf=None, mu_qmaxf=None,  

                             mu_qmint=None, mu_qmaxt=None)
```

Bases: object

This data structure contains key power network dc line parameters.

#### Parameters

- **index** (*int*) – unique dc line identifier

- **f\_bus** (*int*) – the identifier of the from bus
- **t\_bus** (*int*) – the identifier of the to bus
- **br\_status** (*int*) – dc line status (in service = 1, out of service = 0)
- **pf** (*float*) – from bus active power flow (MW)
- **pt** (*float*) – to bus active power flow (MW)
- **qf** (*float*) – from bus reactive power flow (MVar)
- **qt** (*float*) – to bus reactive power flow (MVar)
- **vf** (*float*) – from bus voltage magnitude setpoint (volts p.u.)
- **vt** (*float*) – to bus voltage magnitude setpoint (volts p.u.)
- **pmin** (*float*) – active power flow lower bound (MW), from bus if  $\geq 0$ , to bus if  $< 0$
- **pmax** (*float*) – active power flow upper bound (MW), from bus if  $\geq 0$ , to bus if  $< 0$
- **qminf** (*float*) – from bus reactive power flow lower bound (MVar)
- **qmaxf** (*float*) – from bus reactive power flow upper bound (MVar)
- **qmint** (*float*) – to bus reactive power flow lower bound (MVar)
- **qmaxt** (*float*) – to bus reactive power flow upper bound (MVar)
- **loss0** (*float*) – constant term in from bus active power loss function (MW)
- **loss1** (*float*) – linear term in from bus active power loss function (scalar)
- **mu\_pmin** (*float*, *optional*) – KKT multiplier on from bus active power lower bound (u/MW)
- **mu\_pmax** (*float*, *optional*) – KKT multiplier on from bus active power upper bound (u/MW)
- **mu\_qminf** (*float*, *optional*) – KKT multiplier on from bus reactive power lower bound (u/MVar)
- **mu\_qmaxf** (*float*, *optional*) – KKT multiplier on from bus reactive power upper bound (u/MVar)
- **mu\_qmint** (*float*, *optional*) – KKT multiplier on to bus reactive power lower bound (u/MVar)
- **mu\_qmaxt** (*float*, *optional*) – KKT multiplier on to bus reactive power upper bound (u/MVar)

**to\_matpower** ()

Returns: a Matpower encoding of this data structure as a string

**validate** ()

Checks that this data structure conforms to the Matpower data specification

**class** grg\_mpdata.struct.DCLineCost (*index*, *model*, *startup*=0, *shutdown*=0, *ncost*=0, *cost*=[])

Bases: `grg_mpdata.struct.MatpowerCost`

This data structure contains key power generator cost model parameters. Note that the generator cost identifier (i.e. *index*) is used to link the cost model to a particular generator

The piecewise linear model  $f(x)$  is defined by, the coordinates  $(cost_0, cost_1)$ ,  $(cost_2, cost_3)$ ,  $\dots$ ,  $(cost_{2ncost-1}, cost_{2ncost})$  of the end/break-points of the piecewise linear cost.

The polynomial cost model is defined as,  $f(x) = \sum_{i \in 1..ncost} cost_{i-1} x^{ncost-i}$ .

### Parameters

- **index** (*int*) – unique generator cost identifier
- **model** (*int*) – generator cost model (piecewise linear = 1, polynomial = 2)
- **startup** (*float*) – startup costs (US Dollars)
- **shutdown** (*float*) – shutdown costs (US Dollars)
- **ncost** (*int*) – number of data points or cost coefficients
- **cost** (*list of float*) – the list of data points or cost coefficients (US Dollars/hour), if a polynomial model it should have ncost values, if a piecewise linear model it should have 2\*ncost values

```
class grg_mpdata.struct.Generator (index, gen_bus, pg, qg, qmax, qmin, vg, mbase, gen_status,  

                                     pmax, pmin, pc1=0, pc2=0, qc1min=0, qc1max=0,  

                                     qc2min=0, qc2max=0, ramp_agc=0, ramp_10=0,  

                                     ramp_30=0, ramp_q=0, apf=0, mu_pmax=None,  

                                     mu_pmin=None, mu_qmax=None, mu_qmin=None)
```

Bases: object

This data structure contains key power generator parameters. Some arguments have default values of 0 for backward compatibility with an older data specification.

### Parameters

- **index** (*int*) – unique generator identifier
- **gen\_bus** (*int*) – the identifier of the bus that this generator is connected to
- **pg** (*float*) – active power output (MW)
- **qg** (*float*) – reactive power output (MVar)
- **qmax** (*float*) – reactive power output upper bound (MVar)
- **qmin** (*float*) – reactive power output lower bound (MVar)
- **vg** (*float*) – voltage magnitude setpoint (volts p.u.)
- **mbase** (*float*) – machine mva base (MVA)
- **gen\_status** (*int*) – generator status (in service > 0, out of service <= 0)
- **pmax** (*float*) – active power output upper bound (MW)
- **pmin** (*float*) – active power output lower bound (MW)
- **pc1** (*float*) – PQ capability curve, active power lower bound (MW)
- **pc2** (*float*) – PQ capability curve, active power upper bound (MW)
- **qc1min** (*float*) – reactive power output lower bound, at PC1 (MVar)
- **qc1max** (*float*) – reactive power output upper bound, at PC1 (MVar)
- **qc2min** (*float*) – reactive power output lower bound, at PC2 (MVar)
- **qc2max** (*float*) – reactive power output upper bound, at PC2 (MVar)
- **ramp\_agc** (*float*) – AGC ramp rate (MW/min)
- **ramp\_10** (*float*) – ramp rate for 10 minute reserves (MW)
- **ramp\_30** (*float*) – ramp rate for 30 minute reserves (MW)
- **ramp\_q** (*float*) – ramp rate for reactive power (MVar/min)

- **apf** (*float*) – area participation factor
- **mu\_pmax** (*float*, *optional*) – KKT multiplier on active power output upper bound (u/MW)
- **mu\_pmin** (*float*, *optional*) – KKT multiplier on active power output lower bound (u/MW)
- **mu\_qmax** (*float*, *optional*) – KKT multiplier on reactive power output upper bound (u/MVAr)
- **mu\_qmin** (*float*, *optional*) – KKT multiplier on reactive power output lower bound (u/MVAr)

**to\_matpower** ()

Returns: a Matpower encoding of this data structure as a string

**validate** ()

Checks that this data structure conforms to the Matpower data specification

**class** grg\_mpdata.struct.**GeneratorCost** (*index*, *model*, *startup*=0, *shutdown*=0, *ncost*=0, *cost*=[])

Bases: *grg\_mpdata.struct.MatpowerCost*

This data structure contains key power generator cost model parameters. Note that the generator cost identifier (i.e. *index*) is used to link the cost model to a particular generator

The piecewise linear model  $f(x)$  is defined by, the coordinates  $(cost_0, cost_1)$ ,  $(cost_2, cost_3)$ ,  $\dots$ ,  $(cost_{2ncost-1}, cost_{2ncost})$  of the end/break-points of the piecewise linear cost.

The polynomial cost model is defined as,  $f(x) = \sum_{i \in 1..ncost} cost_{i-1} x^{ncost-i}$ .

#### Parameters

- **index** (*int*) – unique generator cost identifier
- **model** (*int*) – generator cost model (piecewise linear = 1, polynomial = 2)
- **startup** (*float*) – startup costs (US Dollars)
- **shutdown** (*float*) – shutdown costs (US Dollars)
- **ncost** (*int*) – number of data points or cost coefficients
- **cost** (*list of float*) – the list of data points or cost coefficients (US Dollars/hour), if a polynomial model it should have *ncost* values, if a piecewise linear model it should have  $2*ncost$  values

**class** grg\_mpdata.struct.**MatpowerCost** (*index*, *model*, *startup*=0, *shutdown*=0, *ncost*=0, *cost*=[])

Bases: *object*

This data structure contains key power generator cost model parameters. Note that the generator cost identifier (i.e. *index*) is used to link the cost model to a particular generator

The piecewise linear model  $f(x)$  is defined by, the coordinates  $(cost_0, cost_1)$ ,  $(cost_2, cost_3)$ ,  $\dots$ ,  $(cost_{2ncost-1}, cost_{2ncost})$  of the end/break-points of the piecewise linear cost.

The polynomial cost model is defined as,  $f(x) = \sum_{i \in 1..ncost} cost_{i-1} x^{ncost-i}$ .

#### Parameters

- **index** (*int*) – unique generator cost identifier
- **model** (*int*) – generator cost model (piecewise linear = 1, polynomial = 2)
- **startup** (*float*) – startup costs (US Dollars)



- **shutdown** (*float*) – shutdown costs (US Dollars)
- **ncost** (*int*) – number of data points or cost coefficients
- **cost** (*list of float*) – the list of data points or cost coefficients (US Dollars/hour), if a polynomial model it should have ncost values, if a piecewise linear model it should have 2\*ncost values

**to\_matpower** ()

Returns: a Matpower encoding of this data structure as a string

**validate** ()

Checks that this data structure conforms to the Matpower data specification

## 2.5 Module contents

a package for reading and writing of matpower data files



## CHAPTER 3

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